

# Madelung Deformity: Surgical Correction with Radial Dome Osteotomy

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## Abstract

Madelung deformity is a rare wrist malformation caused by a growth disturbance of the palmar and ulnar part of the distal radial physis. The aim of this study is to evaluate the outcome of radial dome osteotomy in patients affected by Madelung deformity. The endpoint of this operation is to improve the orientation of the articular surface of the radius, so as to support to the carpal bones. Between 2017 and 2019, in our clinic, 4 patients were treated using this technique. Postoperative pain was evaluated using the NRS. Functional outcomes were assessed through evaluation of ROM, grip strength via Jamar dynamometer and using DASH questionnaire. The aesthetic defects were estimated using a section of the Michigan Hand Outcome Questionnaire. Correction of deformities was evaluated on post-operative RX using McCarroll Criteria. We also analyzed the accuracy and tolerance of the plates used.

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**Index terms**— madelung, deformity, radial dome osteotomy, piezosurgery, wrist 3D.

## 1 Introduction

Madelung deformity is a rare wrist malformation consisting of excessive radial and palmar angulation of the distal radius caused by a growth disorder of the palmar and ulnar part of the distal radius physis. This leads to shortening and angulation (recurvatio) of the epiphysis, causing a pathognomonic inclination of articular surface palmarly and ulnarly.

Shortening of the radius may cause the development of progressive incongruency at the DRUJ and a positive ulnar variance. This carries to a dorsal subluxation of the distal ulna, causing the altered aspect of the wrist with the prominent ulna.

Step-by-step alterations of the distal radius and the DRUJ are important contributor factors of the so-called carpus pyramidalization, a progressive increase of carpus convexity, and of the volar carpus subluxation.

Other anomalies described are:

• Vickers ligament or radio-lunate ligament. It is an accessory volar ligament hypertrophic connecting distal radius metaphysis, TFCC, and volar surface of lunate. It is responsible for a compressive injury at the ulnar side of the distal radius physis and a proximal traction of the lunate, determining its collapse between radius and ulna [1][2].

• Volar radio-triquetral ligament. It may be present dorsally to Vickers ligament. It is characterized by greater dimension and distal insertion to triquetrum [3][4][5].

• Anomal insertion of pronator quadratus muscle 6 and presence of accessory muscles.

Madelung deformity is a rare condition, the incidence is unknown, and there is no described racial predominance.

Usually, patients come to medical observation between 8 and 14 years old, although there are in literature cases of Madelung deformity at birth or childhood. It is more common in females, the M:F rate of the disorder is 1:4. Madelung deformity can be bilateral about in a third of patients. It may be associated with Léri-Weill dischondrosteosis [7]. There are several types of Madelung deformity [8]:

• Dysplastic type is the more common. It is associated to Léri-Weill dischondrosteosis; Clinically, patients complain of movement-related pain, altered aspect of the wrist, functional limitations especially in pronosupination.

45 In literature several therapeutic options are reported [9][10][11] , but because of the limited number of cases,  
46 due to low incidence, it is difficult to determine the efficacy of proposed treatment strategies.

47 ? Wait & see for asymptomatic or paucisymptomatic cases; ? Surgery: correction of deformity, release of  
48 Vickers ligament and arthrodesis o shortening osteotomy of the ulna.

49 In the present study, we report our experience in surgical correction of Madelung deformity with the release  
50 of Vickers ligament, distal convexity dome osteotomy of the distal radius, and reverse wedge.

## 51 2 II.

### 52 3 Materials and Methods

53 Between 2017 and 2019, four patients (2 males and 2 females) affected by Madelung deformity were treated in  
54 our clinic.

55 Three adolescents aged between 12-14 yearsold and a 30-year-old adult. Three patients had a bilateral  
56 Madelung deformity with a mild deformity in the untreated limb (tab.1).

57 For preoperative planning (fig. 1) we acquired plain radiographs (AP, LL, and oblique projections), MRI to  
58 evaluate surrounding soft tissue (in particular presence/absence of Vickers ligament), and CT scans for better  
59 analysis of the deformity.

60 CT scan data were sent to a workstation in standard DICOM format (PACS, Carestream) to create 3D models  
61 of the affected wrist. For all patients polyamide templates of the deformed wrists (scale 1:1) were manufactured  
62 using a 3D-printer. Harley et al. [12][13] in 2006 and then in 2013 described a surgical correction with dome  
63 osteotomy of the distal radius. The technique described provides a dome osteotomy with distal concavity for  
64 biplanar Use of 3D-printed polyamide template in preoperative planning allowed to evaluate rotational center  
65 of deformity, plan the osteotomy, evaluate needed degrees for triplanar correction, choose implants and simulate  
66 preoperatively surgical procedure.

67 Preoperative planning using 3D virtual planning and 3D-printed templates improves accuracy of surgical  
68 correction with dome osteotomy and reduces surgical duration.

69 It was used a Henry approach, modified according to Orbay, for all the patients in this serie. Release of Vickers  
70 ligament in cases where it was present. After identification of rotational center and level of osteotomy, such as  
71 preoperative planning, using a piezoelectric saw (piezosurgery), it was possible to improve the accuracy of the  
72 osteotomy and the biplanar correction of the deformity with no risk of thermal necrosis.

73 In 2 cases it was also needed a bone wedge excision of the radial column for better correction of the deformity  
74 on the frontal plane. Then the excised bone fragment was used as auto-graft to fill the gap of dome osteotomy  
75 (reverse wedge), allowing faster consolidation and improving stability.

76 Low-profile mouldable plates were used for fixation because of better adaptability rather than anatomical  
77 pre-contoured. At least three screws proximal and three distal to osteotomy were used to fix the plate, avoiding  
78 physis and DRUJ. In one case it was noted the absence of the pronator quadratus associated with the presence  
79 of palmaris profundus muscle. The latter anomaly was already described in literature 14 .

80 After surgery, immobilization of the wrist for 3 weeks in a thermoplastic splint was applied to all patients.  
81 After this period of immobilization, the wrist and forearm rehabilitation protocol were started for about 6 weeks  
82 under the supervision of a hand therapist.

83 Between 8 and 12 months postoperative plates were removed in order to low the incidence of complication  
84 such as tendinitis, infections, and loosening.

85 The mean follow-up duration was 21 months (range 15-28 months). During this period patients were evaluated  
86 like proposed by Peymani et al. 15 in his review. Radiographically McCarroll criteria 16 were used to judge  
87 correction, we evaluated ROM clinically, grip strength via Jamar dynamometer. DASH questionnaires were  
88 administered to evaluate functional outcomes, NRS to quantify subjective pain. Finally, the aesthetic defects  
89 were estimated using a section of the Michigan Hand Outcome Questionnaire.

90 These data were related to collected data before surgery.

## 91 4 III.

### 92 5 Results

#### 93 6 Post-operative radiographs, according to

94 McCarroll criteria, showed a reduction of ulnar tilt, lunate fossa angle, and palmar tilt; whereas no significant  
95 difference of palmar carpal displacement was found (Table2). There were significant improvements in functional  
96 outcomes after surgical correction as suggested by DASH scores, mean score 13/100. It has to be considered that  
97 only the adult patient answered the work-related section of the DASH questionnaire. The MHOQ scores were  
98 improved in all patients on average 30/100 (Table 4).

## 99 7 Discussion

100 The purpose of surgical correction in patients affected by Madelung deformity is to relieve pain and improve  
101 wrist functions supporting the lunate.

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102 The pain was relieved in all patients, 2 of them were totally pain-free. Analysis of postoperative ROM, grip  
103 strength via Jamar dynamometer, and the DASH scores showed good results. Improved MHOQ scores suggested  
104 good aesthetic correction.

105 Corrective dome osteotomy was evaluated on post-operative radiographs, analyzing the degree of correction  
106 according to McCarroll criteria. There was a reduction of pathological angles obtaining in some cases a value  
107 close to physiological. However, the aim of surgery is not to restore radius but is to improve wrist functions,  
108 avoiding lunate collapse. Therefore, it is important that surgery leads to correction of ulnar tilt, lunate fossa  
109 angle, and palmar tilt. In our study, we obtained correction of all these parameters.

110 There was no difference in palmar carpal displacement values between pre and post-surgical correction. PCD  
111 measures the palmar-directed displacement of the carpus (represented by the lunate and capitate) relative to  
112 the longitudinal axis of the ulna in the lateral view. There was no correction of PCD values because it was  
113 not made any surgical correction of the ulna in contrast with the surgical procedure described by Harley et al.  
114 The choice not to modify the deviation of the ulnar longitudinal axis surgically was made so as not to interfere  
115 with prono-supination movements since patients showed good ROM preoperatively. The range of motion may  
116 worsen if we modify the delicate equilibrium made by the gradual dysmorphic growth of articular surfaces aiming  
117 to physiological anatomy that is not present in DRUJ.

118 Eventual surgical correction of the ulna may be considered at the end of the skeletal growth (predominantly  
119 for aesthetic reasons).

120 Some limits to the McCarroll criteria, since x-ray projections are operator dependent, is to always obtain perfect  
121 AP and LL x-ray projections. This limit may be overcome using a preoperative CT scan that are improved with  
122 3D reconstructions and/or MRI.

123 Compared to other techniques reported in the literature for the surgical correction of Madelung deformities,  
124 our technique appeared to be less invasive with shorter recovery time and improved patient's quality of life.

125 McCarroll and James 17 described a combined technique that includes osteotomies of radius and ulna (very  
126 distal radius osteotomy) through a dorsal approach. The same authors highlight an important limitation of the  
127 surgical technique in pediatric patients because fixation has to be made very close to the physal growth plate.

128 Our technique allows to extend the indications to very young patients because the dome osteotomy and the  
129 fixation are made more distant to the physal growth plate.

130 Another limit showed by McCarroll and James is the development of a post-surgical DRUJ instability, often  
131 asymptomatic. This is another contributing factor for our choice not to correct surgically the ulna. Dome  
132 osteotomy showed some common points with cylindrical corrective osteotomy for Madelung deformity proposed  
133 by Imai et al. 18 . Both techniques agree to the fundamental use of CT scan and the case report used a dedicated  
134 software for the preoperative planning, for the line of osteotomy, and to create custom-made cutting guides.

135 Custom-made cutting guide improve surgical accuracy to the preoperative planning, but they limit ulnar  
136 column lengthening, using bone wedge excised from radial column osteotomy (reverse wedge).

137 The use of a pre-op 3D printed model improves surgeons' evaluation and pathology by way of tactile and  
138 visual experience 19 . Furthermore, this technology supports the surgeon by selecting the most adequate device  
139 for osteosynthesis and helps patients and parents to understand the surgical procedure they will undergo. 20 V.

## 140 8 Conclusions

141 The experience with our patients (even if not statistically significant) showed encouraging results in the use of  
142 radial dome osteotomy for the correction of Madelung's deformity.

143 Our experience suggests that the use of 3D printed bone models in preoperative planning improves accuracy  
144 on surgical procedure and on the choice of implants.

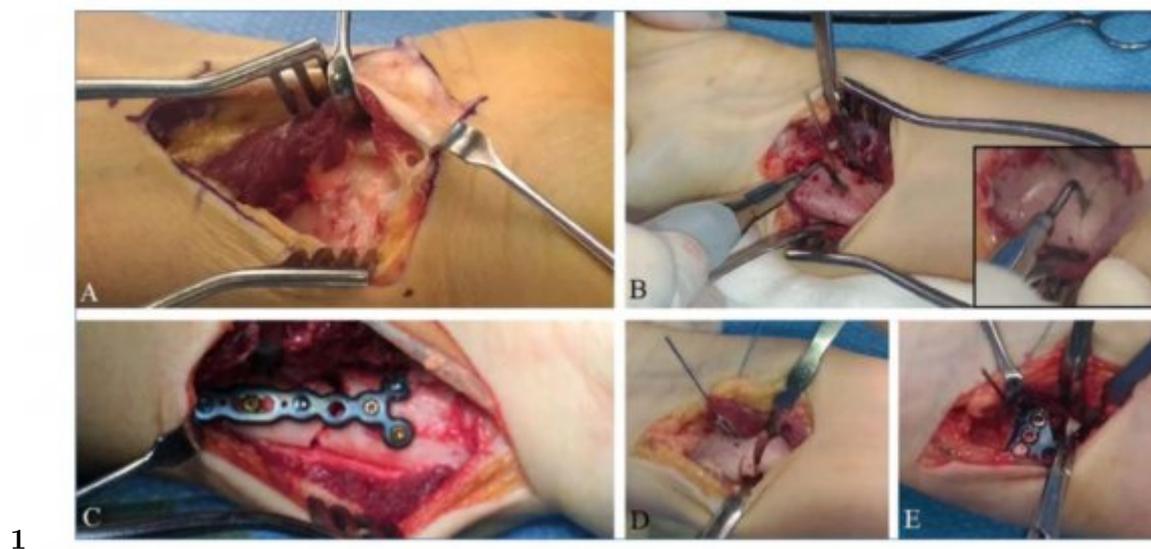
145 In the near future, thanks to a larger sample, our effort will be to standardize this technique as much as  
146 possible, providing precise and adaptable indications to each individual case in order to improve the preoperative  
147 planning aiming to achieve even better surgical results. <sup>1</sup>

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Figure 1:



1

Figure 2: Picture 1 :

**1**

- o Surgical correction of the radius: physiolytisis with or without release of Vickers ligament; opening or closed wedge osteotomies; reverse wedge osteotomy;
- o Surgical correction of the ulna: epiphysiodesis; shortening osteotomy, Darrach's technique; Sauvè-Kapandji technique;
- o Combined surgery on radius and ulna;
- o Release of Vickers ligament

Pz	Age	Bilateral	Treated limb	Follow up (months)	Form	Vickers ligament
1	3	yes	right	15	Idiopathic	Yes
2	12	yes	right	26	Genetic: Léri-Weill	Yes
3	13	yes	left	16	Idiopathic	No
4	13	no	right	28	Idiopathic	No

Figure 3: Table 1 :

**2**

Pz	UT	LS	LFA	PCD	PT
1	*48.7°	*21 mm	*50,8°	*27 mm	*27,8°
	**38°	**9 mm	**33,1°	**27 mm	**18,1°
2	*60,3°	*3 mm	*56,6°	*20,5 mm	*21,3°
	**41,7°	**4,95 mm	**45°	**24 mm	**16,6°
3	*45°	*6,82 mm	*48,3°	*22 mm	*52,6°
	**31°	**6,63 mm	**33,9°	**22 mm	**41,1°
4	*43,6°	*12 mm	*51,3°	*31 mm	*21,5°
	**41°	**6 mm	**47a°	**27mm	**17,4°

UT = ulnar tilt; LS = lunate subsidence; LFA = lunate fossa angle; PCD = palmar Carpal displacement; PT = palmar tilt.

[Note: \*preoperative; \*\* postoperative.]

Figure 4: Table 2 :

**3**

Pz	Grip strength	Pain (NRS)	F	E	Range of motion UD RD	S	P
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Figure 5: Table 3 :

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Pz	DASH	MHOQ
1	*19,4/100 **11,1/100	*50/100 **75/100
2	*51,62/100 **45/100	*62,5/100 **50/100
3	*22,4/100 **7,76/100	*68,75/100 **93,75/100
4	*34,17/100 **11,16/100	*18,75/100 **43,75/100
IV.		

Figure 6: Table 4 :

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